## CHAPTER 1 INTRODUCTION

The carton in which the BDE－2007 is delivered contains： 1．Indicator．2．Accessory pack（In bag）．3．Manual．


2


## CHAPTER 2 INSTALLATION

## § 2－1 Best Conditions For Use

When installing and wire connecting on BDE－2007，please follow the guidelines below：
© Before connecting the Electric Power Supply，please identify the input Electric voltage type is DC 12 V or DC 24 V ．
（）The Operation Temperature shall range within $0^{\circ} \mathrm{C} \sim 45^{\circ} \mathrm{C}$ ，please DO not install in any place of direct sun－light．Due to the minute output signal from Load Cell， please use isolated cables．Also，separate the Load Cell cable from the power supply cable and control I／O cables．
© The input power shall be DC 12 V or $\mathrm{DC} 24 \mathrm{~V} \pm 10 \%$ ，if the Electric Power Supply is not stable or the interference signal exists，that may cause uncertain actuation or reaction，even damage． Therefore，please utilize Electric Power Supply Stabilizer of adequate capacity．

## § 2－2 Connecting the Load Cell

－Do not turn on your power until you have completely connected the load cell．


| Screw | Signal |
| :---: | :--- |
| $\mathbf{1}$ | Positive Excitation Voltage，（EXC＋） |
| $\mathbf{2}$ | Positive Sense Voltage，（SEN＋） |
| $\mathbf{3}$ | Negative Sense Voltage，（SEN－） |
| $\mathbf{4}$ | Negative Excitation Voltage，（EXC－） |
| $\mathbf{5}$ | Positive Signal Voltage，（SIG＋） |
| $\mathbf{6}$ | Negative Signal Voltage，（SIG－） |
| $\mathbf{7}$ | Shield，（SHD） |

> Open the case，there is a jumper〔S1〕near the transformer，please insert a short－circuit pin to the available side．

（i）To connect your load cell to the weighing Indicator use a six－wire cable with shield－connect the wires as indicated above．If the BDE－2007／BDE－2007 is located near the Load Cells（Within five meters or a few yards）you may use a 4 －wire cable with shield，but first connect screws $1 \& 2$ and 3\＆4 with independent jumper leads．
（i）The analogue output from the Load Cell and input／output signals are sensitive to electrical noise．Do not bind these cables together as it could result in cross－talk interface．Please also keep them away from AC power cables．

## § 2-3 Front and Rear Panel Dimensions



Front Panel of BDE-2007


Rear Panel of BDE-2007


## 93.5 mm



CHAPTER 3 SPECIFICATIONS

## § 3-1 Analog Input and A/D Conversion

| OAnalog Input and A/D Conversion |  |
| :--- | :--- |
| Type | BDE-2007 |
| Input Sensitivity | $0.12 \mu$ V/D or above |
| ZERO Adjustment Range | $0 \sim 20 \mathrm{mV}$ |
| Load Cell Excitation | DC5V $\pm 5 \%$, 120mA, <br> Remote Sensing. Can be <br> connected up to $8350 \Omega$ <br> Load Cells. |
| Non-Linearity | $0.01 \%$ F.S. |
| A/D Conversion Method | $\triangle \Sigma$ |
| A/D Resolution | $\fallingdotseq 1 / 1,000,000$ |
| A/D Conversion Rate | 120 Times $/$ Sec. |
| Max. Load Cell Input | 20 mV |
| Voltage |  |

## § 3-2 General

| General |  |
| :--- | :--- |
| Type | BDE-2007 |
| Power <br> Requirements | DC 12 V or $24 \mathrm{~V} \pm 10 \%, 400 \mathrm{~A}$ |
| Net weight | $\fallingdotseq 0.4 \mathrm{~kg}$ |
| Operation <br> Temperature | $-10^{\circ} \mathrm{C} \sim 45^{\circ} \mathrm{C}$ |
| Maximum | $85 \%$ ( non-condensing ] |
| Physical <br> Dimensions | $160(\mathrm{D}) \times 99(\mathrm{~W}) \times 49(\mathrm{H}) \mathrm{mm}$ |

## s3-3 Display and signs

## *3-3-1 Front Panel of BDE-2007



| No. | Display | Spec. |
| :---: | :---: | :---: |
| (1) | 8.8.8.8.8.8 | 6 digit (Positive) |
| (2) | K g , t, lb | Weight indication |
| (3) | ZER0, M. D. , NET, TARED | Status indication ZERO <br> M. D. (Unstable) <br> NET TARED |
| (4) |  | Key |
| (5) | - | DC Voltage low |

## * 3-3-2 Operation Modes

Press Mode key for more than 2 seconds and release, the LED light will change as follows : MODE0 (No light) $\rightarrow$ MODE1 (Red light) $\rightarrow$ MODE2 (Green Light) $\rightarrow$ MODE3 (Orange light)

1.MODE0: Normal Weight display mode.
2.MODE1 (Red): Batch operation mode
3.MODE2 (Green): Set point and Accumulation Mode.
4.MODE3 (Orange): Not in Use.
**Press ZERO keys more than 2 seconds will escape.
** See 5-1 to learn setup of set point values.

| Mode | $\begin{gathered} \text { Press MODE } \\ \text { To } \end{gathered}$ | $\begin{aligned} & \text { Press } \\ & \text { ZERO } \\ & \text { To } \end{aligned}$ | $\begin{gathered} \text { Press TARE } \\ \text { To } \end{gathered}$ | $\begin{gathered} \text { Press GIN } \\ \text { To } \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: |
| Mode 0 | Manual Accumulation $=$ Press mode key 1 second. | ZER0 | Tare $=$ Press mode key 1 second. <br> Tare Clear=Press mode key >2 second. | Gross / Net Change |
| Mode 1 (RED) | Manual Accumulation = Press mode key 1 second. | ZERO | Tare $=$ Press mode key 1 second. <br> Tare Clear=Press mode key $>2$ second. | Batching Start/ Stop |
| Mode 2 (Green) | ENTER $=$ Press <br> mode key 1 <br> second.   | Set Point | Display Accumulation | Up and down |
| Mode 3 (Orange) | Not in Use |  |  |  |

* 3-3-3 Rear Panel


| No. | Spec. |
| :---: | :---: |
| $(1)$ | DC power input |
| $(2)$ | Serial |
| $(3)$ | Load cell input 7 pins |
| $(4)$ | SET cover |
| $(5)$ | Option cover |
| $(6)$ | Grounding |

## CHAPTER 4 SYSTEM UNCTIONS



## § 4-1 System Check

A system check should be run: after initial installation, after moving your BDE-2007, after connecting or disconnecting an attachment from the Rear Panel and as means of locating any unexplained system error.
STEP 1: Power OFF, make sure all SET $\left.{ }^{2}{ }^{1}\right]_{\text {off }}$.
STEP 2: Power ON, Press MODE
With ZERO key more than 2 seconds, displayed F-CSET $\rightarrow$ FUNC.
STEP 3:Press TARE key, shows CHECK.
STEP 4:Press MODE Key, the system will check 7 Segment Leeds in sequence., When show EE-1, Slide Set 1 [100 , then press MODE key, System will Check MEMORY 〔EEPROM〕 shows I-0, it means system error.
STEP 7:System check will go to Input/Output checking. When the screen show I-O, Subsequently, the screen will show OUTPUT. Please make SHORT-CIRCUIT test on 25-Pin D shape Output on the rear panel. When short-circuiting COM17 or COM16 with other pins, the short-circuit pin will light up a specific LED on the screen. If not, there suggests an error occurred.
STEP 8:Check keypad. ( $1,2,3,4$ ). When pressing a key, the key number will show in the middle of the screen: KEY 01~KEY 4. If the key number does not match, it suggests an error occurred. Please contact us.
STEP 9: Finish checking, Slide SET BDE-2007 will back to normal mode.

## § 4-2 Functions

STEP 1: Press MODE With ZERO key more than 2 seconds, displayed F-CSET $\rightarrow$ FUNC.
STEP 2: Press MODE key to show F000 afterward.
STEP 4:Please press TARE or G/N key to go up and down (F000, F200, F300, F400 or F500). Then press the MODE Key to enter the category. Press MODE key to enter.
(i) If any errors occurred, please check if each setting value within effective range.

STEP 5: When you finished changing the Function setting, Press ZERO key more then 2 seconds to escape,
©General Functions

| F000 | Decimal Point Adjustment |  |  |
| :---: | :---: | :--- | :--- |
|  | 0 | No Decimal | 123456 |
|  | 1 | 1 Decimal | 12345.6 |
|  | 2 | 2 Decimal | 1234.56 |
| 0 | 3 | 3 Decimal | 123.456 |


| F001 | Weighing Unit Selection |  |
| :---: | :---: | :--- |
|  | 0 | None |
|  | 1 | kg |
|  | 2 | ton |
|  | 3 | Lb |


| F002 | Display Update Rate |  |
| :---: | :---: | :---: |
|  | 0 | 5 Times $/ \mathrm{Sec}$ |
|  | 1 | 10 Times $/ \mathrm{Sec}$ |
|  | 2 | 20 Times $/ \mathrm{Sec}$ |
|  | 3 | 40 Times $/ \mathrm{Sec}$ |


| F004 | Set ZERO Range |  |
| :---: | :---: | :--- |
|  | 5 | $\pm 5 \%$ of weighing platform <br> Full Capacity |
|  | 10 | $\pm 10 \%$ of weighing platform <br> Full Capacity |
|  | 20 | $\pm 20 \%$ of weighing platform <br> Full Capacity |
| 30 | Full of weighing platform <br> full Capacity |  |


| F003 | Digital Filter |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Filter | Environment <br> Vibration | Response <br> Speed |
|  | 0 | No stage | Weak | Bad | Fast |
|  | 1 | $1^{\text {st }}$ stage |  |  |  |
|  | 2 | $2^{\text {ed }}$ stage |  |  |  |
|  | 3 | $3^{\text {td }}$ stage | $\mathbf{A}$ | $\mathbf{\Delta}$ | $\mathbf{\Delta}$ |
| - | 4 | $4^{\text {th }}$ stage | $\boldsymbol{\nabla}$ | $\boldsymbol{\nabla}$ | $\boldsymbol{\nabla}$ |
|  | 5 | $5^{\text {th }}$ stage |  |  |  |
|  | 6 | $6^{\text {th }}$ stage |  |  |  |
|  | 7 | $7^{\text {th }}$ stage | Strong | Good | Slow |


| F005 | Motion Detection |  |
| :--- | :---: | :--- |
|  | 00 | Stable |
|  | 01 | 0.5 SEC 1 DIV |
|  | 02 | 0.5 SEC 2 DIV |
|  | 03 | 0.5 SEC 3 DIV |
|  | 04 | 0.5 SEC 4 DIV |
|  | 05 | 0.5 SEC 5 DIV |
|  | 06 | 0.5 SEC 6 DIV |
|  | 07 | 0.5 SEC 7 DIV |
|  | 08 | 0.5 SEC 8 DIV |
|  | 11 | 1 SEC 1 DIV |
|  | 12 | 1 SEC 2 DIV |
|  | 13 | 1 SEC 3 DIV |
|  | 14 | 1 SEC 4 DIV |
|  | 15 | 1 SEC 5 DIV |
|  | 16 | 1 SEC 6 DIV |
|  | 17 | 1 SEC 7 DIV |
|  | 18 | 1 SEC 8 DIV |


| F006 | Automatic ZERO <br> Tracking Compensation |  |
| :--- | :--- | :--- |
|  | 00 | OFF |
|  | 11 | 1 SEC 0.5 DIV |
|  | 12 | 1 SEC 1 DIV |
|  | 13 | 1 SEC 1.5 DIV |
|  | 14 | 1 SEC 2 DIV |
|  | 15 | 1 SEC 2.5 DIV |
|  | 16 | 1 SEC 3 DIV |
|  | 17 | 1 SEC 3.5 DIV |
|  | 18 | 1 SEC 4 DIV |
|  | 21 | 2 SEC 0.5 DIV |
|  | 22 | 2 SEC 1 DIV |
|  | 23 | 2 SEC 1.5 DIV |
|  | 24 | 2 SEC 2 DIV |
|  | 25 | 2 SEC 2.5 DIV |
|  | 26 | 2 SEC 3 DIV |
|  | 27 | 2 SEC 3.5 DIV |
|  | 28 | 2SEC 4 DIV |
|  |  |  |

F007 ZERO \& TARE keys Availability

- 0 ZERO \& TARE keys always work 1 ZERO \& TARE keys only work when display is STABLE

F009 Accumulation Availability

|  | 0 | OFF |
| :--- | :--- | :--- |
|  | 1 | Stable |
|  | 2 | Manual |
|  | 3 | Control Input--Command <br> Accumulation (For Modbus) |
| - | 4 | Control Input -Command <br> Accumulation |



F100 Set ZERO Band
6 digit Zero band value ( Initial "000.000")

## F101 Batching Mode

| - | 1 | Customer Programmed Control <br> Mode: Normal Batching |
| :---: | :--- | :--- |
|  | 2Customer Programmed Control <br> Mode: Loss-in-Weight Batching |  |
|  | 3Built-in Automatic Program Mode: <br> Normal Batching |  |
|  | 4Built-in Automatic Program Mode: <br> Loss-in weight Batching |  |

## F103 Timer-Finish Signal

The finish signal timer can be Set between
0.0 to 9.9 Sec
※- Initial 0.0 Sec
※ Finish Signal sent ON at 0.0 Sec .
And stays ON until the next START Signal. ※ (Only apply to batching mode 3 and 4).


| F106 | Input by |  |
| :---: | :---: | :--- |
| $\boldsymbol{~}$ | (Batch start/ stop) |  |
|  | 1 | Panel key |
|  | 2 | BCD Input |
|  | 3 | Serial Input/ Modbus |


| F108 | Memory Automatic Free Fall <br> Compensation |  |
| :---: | :---: | :--- |
| - | 0 | Yes |
|  | 1 | Not Memory |

F102 Timer-Comparator Inhibitor
Set between 0.0 to 2.0 Sec
( Initial 0.0 Sec )
(Only apply to batching mode 3 and 4).

## F104 Pulse Width of Finish Signal

Set between 0.0 Sec to 2.0 Sec
※ - Initial 0.5 Sec
※ Stable at 0.0 Sec. Which is apply to F101 setting at 3 or 4 .


| F105 | Output 8 |  |
| :---: | :---: | :--- |
| $\bullet$ | 0 | Unstable |
|  | 1 | Error |

© SERIAL (RS-232 two way/ RS-485 Modbus)


| F201 | Set data length, Parity, Stop bit |  |
| :---: | :---: | :---: |
|  | 0 | D8,N,1 |
|  | 1 | D7,E,1 |
|  | 2 | D7,O,1 |
|  | 3 | D8,N,2 |
|  | 4 | D8,E,1 |
| 5 |  |  |
| Only 3,4,5 applicable MODBUS (RTU) |  |  |


| F202 | Output data |  |
| :---: | :--- | :--- |
| - | 1 | Same as display |
|  | 2 | GROSS Weight |
|  | 3 | NET Weight |
|  | 4 | TARE Weight |
|  | 5 | GROSS Weight, NET <br> Weight, TARE Weight |


| F203 | Output Mode |  |
| :---: | :---: | :--- |
|  | 1 | Stream |
|  | 2 | Stable and auto print |
|  | 3 | Manual Print Mode |
|  | 4 | Accumulate and Print |
|  | 5 | For RS-232 commanding |
|  | 6 | For Modbus commanding |

F204 $\quad$ Serial address (RS-485)
00-not used(OFactory set at 00)
00-99 Used

| F205 | RS-232 Models select |  |
| :---: | :---: | :--- |
| $\boldsymbol{}$ | 0 | BDI-2001/ AD4321 |
|  | 1 | BDI-9301 |
|  | 2 | IQ-350 |
|  | 3 | $\mathrm{HB}-8210$ |

© Analog Output

| F500 | Analog Output Data |  |
| :---: | :---: | :---: |
| - | 1 | Output 4~20 mA |
|  | 2 | Output 0~+10 V |


| F 502 | Loss-in-weight Absolute <br> Value |  |
| :---: | :---: | :--- |
| 0 | 0 | Not read Absolute <br> Value |
|  | 1 | BDI-2001B reads <br> Absolute Value |


| F501 | Output Mode |  |
| :---: | :---: | :--- |
| $\boldsymbol{O}$ | 1 | Same as display |
|  | 2 | GROSS Weight |
|  | 3 | NET Weight |


| F 503 | Output current when display <br> ZERO |
| :---: | :---: |
| 0.0 through 99.9 |  |
| Initial 4.0 |  |
| (If F 500=1, Normally between 4-20, |  |
| If F 500=2, Normally between 0-10) |  |

F 504 Output current at Full Capacity
0.0 through 9.99

O Initial 20.0
(If F 500=1, Normally between 4-20, If F 500=2, Normally between 0-10)
(o) Serial (RS-232-one way)

| FL00 | Band Rate |  |
| :---: | :---: | :---: |
|  | 1 | $1200 B P S$ |
| $\bullet$ | 2 | $2400 B P S$ |


| FL01 | Output data |  |
| :---: | :---: | :--- |
| $\boldsymbol{0}$ | 1 | Same as display |
|  | 2 | GROSS Weight |
|  | 3 | NET Weight |
|  | 4 | TARE Weight |
|  | 5 | GROSS Weight, NET <br> Weight, TARE Weight |


| FL02 | Output Mode |  |
| :---: | :---: | :--- |
| $\boldsymbol{O}$ | 1 | Stream |
|  | 2 | Stable and auto print |
|  | 3 | Manual Print Mode |
|  | 4 | Accumulate and Print |

## §4－3 Calibration

STEP 1：Power OFF，Power ON，Rear Panel SET 1 （B）ON．Shows CAL $\rightarrow$ F－CAL．
〔1〕Setting Minimum Division
Press MODE key，displays di 01 Use the＋or－key to move through the available divisions．〔01，02，05〕．Press the MODE key to set the minimum division．
〔2〕Setting Decimal（FO00 can also change－－－see § 4－2）
The screen will show dp $\rightarrow$ d000．000．
Use the＋or－key to move through the available divisions．〔01，02，05〕．Press the MODE key to set the minimum division．
〔 3 〕Setting Maximum Capacity
Screen will show CAP $\rightarrow$ C000．000．Use the $<$ or + or－key to move through the available divisions．〔01，02，05］．Press the MODE key to set the minimum division
〔4］ZERO Adjust
The Screen will display ZERO．Please move the calibration mass and objects away on the Weighing device then press MODE key．A display of ．．．．．．．means finishing the Adjustment．
〔5〕 SPAN Calibration
The screen will show SPAN．Press MODE key and place your calibration mass on the weighing device and input weight value．Use the＜or＋or－key to set your mass weight．Press the MODE key to mark the SPAN．The screen will show END．
Slide the SET switch to the original side．

## © Calibration Errors

C．Err 1 ：The resolution exceeds $1: 30,000$ ．
$\Rightarrow$ Change the minimum division and maximum capacity within $1 / 30,000$ ．Resolution ratio $=$ Minimum division／maximum capacity
C．Err 2 ：The load cell output is too large at ZERO calibration．
$\Rightarrow$ Add an additional resistor
（ $50 \mathrm{k} \Omega \sim 500 \mathrm{~K} \Omega$ ）between EXC＋and SIG－．
※ Refer to the Right Figure
C．Err 3 ：The load cell output is too small at ZERO calibration．
$\Rightarrow$ Add an additional resistor
（ $50 \mathrm{k} \Omega \sim 500 \mathrm{~K} \Omega$ ）between EXC＋and SIG＋．
※ Refer to the Right Figure
C．Err 4 ：The calibration mass has been mistakenly entered as a value greater than the maximum capacity．

$\Rightarrow$ Please reduce the weight of calibration mass，and re－enter the weight value．
C．Err 5：The calibration mass has been wrongly entered zero or it is smaller than the minimum capacity．
$\Rightarrow$ Please increase the weight of calibration mass，and re－enter the weight value．
C．Err 6：The load cell output is too low．
$\Rightarrow$ Replace your load cell with a more sensitive one or adjust the minimum division．
C．Err 7：The load cell signal pins are reversed，or the load cell output voltage is too low． $\Rightarrow$ Check the load cell connections if reversed or load cell failure．
C．Err 8：The load cell output voltage at maximum capacity is too high．
$\Rightarrow$ Check the load cell specification or load cell failure．
C．Err 9：The maximum，capacity has been wrongly entered as a value smaller than 100. $\Rightarrow$ Check Resolution Table．
C．Err 10：The maximum，capacity has been wrongly entered as a value greater than 750,000 ． $\Rightarrow$ Check the load cell specification or load cell failure．
C．Err 11 ：Please clear and Tare first
$\Rightarrow$ Please make ZERO calibration first
C．Err 12 ：Input value too big or small．$\Rightarrow$ Input again．

## § 4-4 SYSTEM INITILAIZE

STEP 1: Power OFF, slide rear SET 1
ON.
STEP 2: Screen shows CAL, Press TARE key until show init
STEP 3: Press MODE key, screen will show NO,
STEP 4: Press + key to show YES, Press MODE key to confirm $\rightarrow$ END.
STEP 5: Finish initialize, Slide SET ${ }^{2} \|_{\text {off }}$ and back to normal mode.

## § 4-5 Accumulation

4-5-1 Display Accumulation
In MODE 2 Status,
Press TARE key, the screen will show its total count.
Press TARE again, the screen will show Accumulation.
Press ZERO key more than 2 seconds will escape.

## 4-5-2 Clear Accumulation

Press TARE key more than 2 seconds will show CLR A.C.
Press MODE key to clear count and accumulation.
Press ZERO key more than 2 seconds will Escape.

## CHAPTER 5 SET POINTS

## § 5-1 SET POINTS

## 5-1-1 Change Set point code and Set point values

Press ZERO key to show Final. Press Mode key to show 000.000 , Use $+/-/<$ key to set Final Values. Press Mode key to confirm the Final Value.
Press Mode key to show SP1, Press Mode key to show 000.000 , Use $+/-/<$ key to set Sep point 1 values. Press Mode key to confirm the SP1 value.
Press Mode key to show SP2, Press Mode key to show 000.000 , Use $+/-/<$ key to set Sep point 2 values. Press Mode key to confirm the SP2 value.
Press Mode key to show FREE, Press Mode key to show 000.000 , Use $+/-/<$ key to set Free fall values. Press Mode key to confirm the Free fall value.
Press Mode key to show Hi, Press Mode key to show 000.000 , Use $+/-/<$ key to set Hi limit values. Press Mode key to confirm the Hi value.
Press Mode key to show L0, Press Mode key to show 000.000 , Use $+/-/<$ key to set Lo limit values. Press Mode key to confirm the Lo value.
Press ZERO key more than 2 Seconds to leave.

## § 5-2 BATCHING MODES

## -Batching Modes

1. Customer Programmed Control Mode: Normal Batching
2. Customer Programmed Control Mode: Loss-in-Weight Batching
3. Built-in Automatic Program Mode: Normal Batching
4. Built-in Automatic Program Mode: Loss-in weight Batching
5. Multiple-Ingredient Batching
© Customer Programmed Control Mode: Normal Batching( F101 = 1)


1.The Weighing Hopper is empty, the display shows " 0 ", and all Gates are closed. If the display is not at ZERO, input a TARE signal(Pin 24) to re-ZERO the display.
2.Open the Supply Bin's: Full-Flow Gate,Medium-Flow Gate, and Dribble-Flow Gate.
3.When the display reaches "Final - SP 1", the SP 1 Output (Pin 12) signal will come ON.

Closed the Full-Flow Gate by using the SP 1Output ON signal.
4.When the display reaches "Final - SP 2", the SP 2 Output (Pin 11) signal will come ON. Closed the Medium-Flow Gate by using the SP 2 Output ON signal.
5.When the display reaches "Final - FREE", the FREE Output (Pin 10) signal will come ON.

Closed the Dribble-Flow Gate by using the FREE Output ON signal.
6.After Free Fall has stopped - check if the HI and LO (Pin 9, 8) signals are OFF. If both outputs are OFF then the batch is completed correctly.
7.An Automatic Free Fall Compensation Command (Min. 200ms pulse to Pin 21) may be given at this time. If you change the Free Fall Set Point value either from the Front Panel or the RS-232C, RS-422/485 - the learned Free Fall value will be cleared.
8.Use the FREE (Pin 10) signal to delay a time period as the control signal is processing empty the Weighing Hopper.
9.When the GROSS weight is below the ZERO band, the ZERO Band Output will come ON -signifying the Weighing Hopper is empty. Closed the Weighing Hopper Discharge Gate by using the ZERO Band (Pin 13) Output ON signal.
10. You are now ready for your next batching event.

© Customer Programmed Control Mode: Loss-in-Weight ( F101 = 2)
SP1 - Supplying Bin Gate
SP2 - Full Flow Gate
Free - Dribble Flow Gat


1. The Weighing Hopper is empty as is the Receiving Bin. The display shows " 0 ", and all Gates are closed.
2. Open the Supplying Bin Gate.
3. When the GROSS Weight reaches "SP 1", the SP 1 Output (Pin 12) signal will come ON. Closed the Supplying Bin Gate by using the SP 1 Output ON signal.
4. The displayed weight will exceed the SP 1 value by the Free Fall value. This weight is not necessarily accurate - but accuracy is not needed at this moment since the purpose of this event is to fill up the Weighing Hopper. The SP 1 value is always compared to GROSS weight.
5. Input a TARE signal (Pin 24) to ZERO the display.
6. Open the Full-Flow Gate and the Dribble-Flow Gate for Full-Flow filling into the Receiving Bin.
7. When the display reaches "Final - SP 2", the SP 2 Output (Pin 11) signal will come ON. Closed the Full-Flow Gate by using the SP 2 Output ON signal.
8. When the display reaches "Final - FREE", the FREE Output (Pin 10) signal will come ON. Closed the Dribble-Flow Gate by using the FREE Output ON signal.
9. After Free Fall has stopped - check to see if the HI and LO (Pin 9, Pin 8) signals are OFF. If both outputs are OFF then the batch is completed correctly.
10. An Automatic Free Fall Compensation Command (Min. 200ms pulse to Pin 21) may be given at this time.
11. If the GROSS weight of the Weighing Hopper is below the ZERO Band (Pin 13), the ZERO Band Output will be ON. The ZERO Band Output will refill Weighing Hopper if needed.
12. Ready for next batching event.


Built-in Automatic Program Mode: Normal Batching( F101 = 3 )
SP1 - Full Flow Gate
SP2 - Medium Flow Gate
Free - Dribble Flow Gate
Start signal - Pin22


1. The Weighing Hopper is empty, the display shows " 0 ", and all Gates are closed. If the display is not at ZERO, input a TARE signal (Pin 24) to re-ZERO the display.
2. Check if the Weighing Hopper is empty using the ZERO Band Output (Pin 13).
3. Input the Start signal via the Control I/O Interface connector (Pin 22). When the Start signal is received, then SP 1, SP 2, and Free Output signals will "come ON".

Note: When the Final Weight is 0 , the Pin 12, 11 and 10 are kept OFF.
4. Open the Supply Bin's: Full-Flow Gate, Medium-Flow Gate, and Dribble-Flow Gate.
5. When the display reaches "Final - SP 1", the

SP 1 Output (Pin 12) signal will come OFF. Closed the Full-Flow Gate by using the SP 1 Output OFF signal.
6. When the display reaches "Final - SP 2", the

SP 2 Output (Pin 11) signal will come OFF. Closed the Medium-Flow Gate by using the SP 2 Output OFF signal.
7. When the display reaches "Final - Free", the Free Output (Pin 10) signal will come OFF. Closed the

Dribble-Flow Gate by using the Free Output OFF signal.
8. Batch Finish signal is sent after the set time period (F103) or when the display is stable.
9. After Free Fall has stopped - check to see if the HI and LO (Pin 9, 8) signals are OFF. If both outputs are OFF then the batch is completed correctly.
10. Automatic Free Fall is now recalculated for the next event.
11.The Weighing Hopper Discharge Gate will be opened using the Finish Output (Pin 7) ON signal.
12.Data Output is sent (Auto print Mode: BCD, RS-232C, RS-422/485, Printer or Current Loop). The NET Weight data will be accumulated.
13. Ready for the next batching event.
14. If an Abort signal is sent (Pin 21) anytime after the Start signal is received, then:
(1) SP 1, SP 2 and Free signals will go OFF, and Gates will be closed.
(2) Batch Finish and Data Output signals will be sent.
(3) NET Weight data will be accumulated.


Built-in Automatic Program Mode: Loss-in-Weight Batching (F101=4)
SP1 - Supplying Bin Gate
SP2 - Full Flow Gate Free - Dribble Flow Gate Start signal - Pin22


1. The Weighing Hopper/ Supply Bin is empty .The display shows " 0 ", and all Gates are closed.
2. Open the Supplying Bin Gate.
3. When the GROSS Weight reaches "SP 1", the SP 1 Output (Pin 12) signal will come ON. Closed the Supplying Bin Gate by using the SP 1 Output ON signal.
4. The displayed weight will exceed the SP 1 value by the Free Fall value. This weight is not necessarily accurate - but accuracy is not needed at this moment since the purpose of this event is to fill up the Weighing Hopper. The SP 1 value is always compared to GROSS weight.
5. Input a TARE signal (Pin 24) to ZERO display.
6. Input the Start signal via the Control I/O interface connector (Pin 22). When the Start signal is received, the SP 2 and Free Outputs "come ON".
Note : When the Final Weight is 0, the Pin 11 and 10 are kept OFF .
7. Open the Full-Flow Gate and the Dribble-Flow Gate for Full-Flow filling into the Receiving Bin.
8. When the display reaches "Final - SP 2", the SP2 Output (Pin 11) signal will come OFF. Closed the Full-Flow Gate by using the SP2 Output OFF signal.
9. When the display reaches "Final - FREE", the FREE Output (Pin 10) signal will come OFF. Closed the Dribble-Flow Gate by using the FREE Output OFF signal.
10. Batch Finish signal is sent after the set time period (F103) or when the display is stable.
11. After Free Fall has stopped - check if the HI and LO ( $\mathrm{Pin} 9,8$ ) signals are OFF. If both outputs are OFF then the batch is completed correctly.
12. Automatic Free Fall is now recalculated for the next event.
13. The Weighing Hopper Discharge Gate will be opened using the Finish Output (Pin 7) ON signal.
14. Data Output is sent (Auto print Mode: BCD, RS-232C, RS-422/485, Printer or Current Loop). The NET Weight data will be accumulated.
15. Signal (Pin 13) will refill using ZERO Band Output if needed. Ready for next batching event.
16. Ready for the next batching event.
17. If an Abort signal is sent (Pin 21) anytime after the Start signal is received, then:
(1) SP 1, SP 2 and Free signals will go OFF, and Gates will be closed.
(2) Batch Finish and Data Output signals will be sent.
(3) NET Weight data will be accumulated.


## CHAPTER 6 OPTIONS

## § 6-1 I/O INTERFACE

(0) Controll/O

## Input :



The width of these input pulse should at least 0.25 sec .

## Output :


() INPUT Pins Description When F101 =1, 2.

| Pin | Name | Signal | Function |
| :---: | :---: | :---: | :--- | :--- |
| Pin25 | ZERO Input | pulse | BDE 2007 will zero according to F004 |
| Pin24 | TARE Input | pulse | BDE 2007 will return to zero and store tared weight. |
| Pin23 | TARE Reset | pulse | Clear Tared Weight |
| Pin21 | Auto Free Fall <br> Compen -sation <br> when batching | pulse | When P21 and COM 1 shortage, BDE 2007 will adjust compensation value for next <br> batch. And accumulate Net Weight. |
| Pin18 | lear count and <br> acculmulation. | pulse | Clear count and accumulation. |
| Pin17 <br> li6 | Input Common <br> (COM1) |  |  |

© INPUT Pins Description When F101 =3, 4.

| Pin | Name | Signal | Function |
| :---: | :---: | :---: | :---: |
| Pin25 | ZERO | Pulse | BDE 2007 will zero according to F004 |
| Pin24 | TARE Input | Pulse | BDE 2007 will return to zero and store tared weight. |
| Pin23 | TARE Reset | Pulse | Clear Tared Weight |
| Pin22 | Batch/Loss in <br> Weight Start <br> batch  <br> (Pulse input)  | Pulse | Start Batch |
| Pin21 | $\begin{aligned} & \text { Batch/Loss in } \\ & \text { Weight Stop } \\ & \text { batch } \\ & \text { (Pulse Input). } \\ & \hline \end{aligned}$ | pulse | Stop Batch and send finish signal, and accumulation. |
| Pin18 | Clear count and accumulation. | pulse | Clear count and accumulation. |
| $\begin{array}{\|l} \hline \text { Pin17 } \\ -16 \end{array}$ | $\underset{\substack{\text { Input } \\ \text { (COM1) }}}{ }$ |  |  |


| Pin | Name | F101 | Description |
| :---: | :---: | :---: | :---: |
| Pin13 | ZERO Band |  | Gross Weight $\leqq$ ZERO Band |
| Pin12 | SP1 | 1,3 | Batch : Net Weight > = Final-SP1 |
|  |  | 2,4 | Loss in Weight : Gross Weight $>$ SP1 |
| Pin11 | SP2 |  | Net Weight $>=$ Gross - SP2 |
| Pin10 | FF |  | Net Weight $>=$ Final -FF |
| Pin9 | HI |  | Net Weight $>$ Final + Hi value |
| Pin8 | LO |  | Net Weight < Final-Lo Value |
| Pin7 | FINISH | 3,4 | Batch/ Loss-in Weight : Final Output -Finsh Signal |
| Pin6 | Unstable / <br> Error |  | F105=0: Stable: Open, Unstable : Short. <br> F105=1: Error Output, ZERO exceed valid Range, Overload, or Printer Error. |
| Pin3, 4 | Output 12V |  | Max. 0.5A |
| Pin1 - 2 | COM2 |  |  |

## 5 6-2 Serial interface OP-02

There are two kinds of OP-02 :
(1) High speed two way(Pin3,Pin4)
F200
(2)Low speed one way(Pin1)
FLOO

| Specifications |  |  |
| :---: | :--- | :--- |
| Type | EIA-RS-232C 12V |  |
| Transmission | Half Duplex, Asynchronous Transmission |  |
| Baud Rate | $1200 \cdot 2400, ~ 4800 \cdot 9600 \cdot 19200 \mathrm{BPS}$ |  |
| Bit | 8 bit | 7 bit |
| Parity | non- parity | Odd / even parity |
| Stop bit | 1 bit |  |
| Output Code | ASCII |  |

Specifications

| Transmission | Half Duplex, Asynchronous Transmission |
| :---: | :---: |

Baud Rate 1200, 2400, 4800, 9600, 19200BPS

Parity $\quad$ non- parity $\quad$ Odd / even parity
Output Code ASCII


## * OP-02A (RS-232)

25 Pin assigments

|  | Pin | Assigment |
| :---: | :---: | :---: |
|  | Pin 1 | TxD2 (Transmit Data) |
|  | Pin 2 | SG (Signal Ground) |
|  | Pin 3 | RxD (Receive Data) |
|  | Pin 4 | TxD (Transmit Data) |

* OP-02B (RS-485)

| RS-485 Spec : |  |  |
| :---: | :--- | :--- |
| Type | EIA-RS-485 |  |
| Transmission | Half Duplex, Asynchronous Transmission |  |
| Baud Rate | 2400BPS, 4800BPS, 9600BPS, 19200BPS, 38400BPS |  |
| Bit | 8 bit | 7 bit |
| Parity | non- parity | Odd / even parity |
| Stop bit | 1 bit |  |
| Output Code | ASCII |  |

- Pins when connect PC :


Data format

| F205 $=0$ (standard) |
| :--- |
| format1 (F002) |
| S T , N T , 0 0 5 4 3 2 $\cdot$ |


| ※ HEADER 2 |  |
| :---: | :--- |
| N | $\rightarrow$ NET |
| G | $\rightarrow$ GROSS |
| T | $\rightarrow$ TARE |

$\uparrow$ Header $1 \uparrow$ Header2 $\uparrow$ Data ( 8 digits in length)

| ※ HEADER 1 |  |  |  |
| :---: | :---: | :---: | :---: |
| 0 | L | $\rightarrow$ Over Max. Capacity or under |  |
| S | T | $\rightarrow$ STABLE |  |
| U | S | $\rightarrow$ UNSTABLE |  |
| ASCII data characters |  |  |  |
| " 0 " ${ }^{\text {a }}$ " 9 " |  |  |  |
| " " Space (20H) |  |  |  |
| " . " Decimal Point (2EH) |  |  |  |
| " - " Minus (2DH) |  |  |  |
| " ${ }^{-}$+ ${ }^{-} \quad$ Minus (2DH) |  |  |  |

※Command List Table

| Sending Command to <br> BDE-2007 | BDE-2007 response |
| :--- | :--- |
| R01 Cr Lf <br> $\langle$ READ $\rangle$ | Sending latest data once <br> (Data format depends on F202) |
| K01 Cr Lf <br> $\langle$ ZERO $\rangle$ | BDE-2007 display will ZERO. <br> Z Cr Lf will be sent by BDE-2007. |
| K02 Cr Lf <br> $\langle$ TARE $\rangle$ | BDE-2007 will go to NET Mode and display will TARE. <br> T Cr Lf will be sent by BDE-2007. |
| K04 Cr Lf | BDE-2007 will go to NET Mode. <br> N Cr Lf will be sent by BDE-2007. |
| $\langle$ NET $\rangle$ | BDE-2007 will go to GROSS Mode. <br> G Cr Lf will be sent by BDE-2007. |
| K03 Cr Lf <br> $\langle$ GROSS $\rangle$ |  |


| Sending Command to <br> BDE-2007 | BDE-2007 response |
| :---: | :--- |
| C01 Cr Lf <br> $<$ BEGIN BATCHING $>$ | Send back signal "BB". "BB" can only be received in the <br> Built in Automatic Program Control Mode. (Only F101=2,3) |
| C02 Cr Lf <br> $<$ HALT BATCHING $>$ | Send back signal "HB". "HB" an only be received in the <br> Built in Automatic Program Control Mode (Only F101=2,3) |
| R04 Cr Lf <br> $<$ READS FINAL NET $>$ | Sending Final NET weight. If B Cr Lf is send by BDE-2007, <br> that means batching is still in process. (Only F101=2,3) |
| W02: Data Cr Lf <br> $<$ SETPOINT $>$ | Signal "S Cr Lf" will send back by BDE-2007. <br> BDE-2007 will send back SET POINT CODE until totally <br> receive SET POINT CODE data. |


| R03 Cr Lf <br> $<$ READ SETPOINT $>$ | SS XX Cr Lf will send back by BDE-2007. <br> BDE-2007 will send back SET POINT values until totally <br> receive SET POINT values. |
| :---: | :--- |
| W01: Data Cr Lf <br> $<$ SET ACCESSORIES $>$ | BDE-2007 will send back signal "SA Cr Lf". <br> BDE-2007 will send back ZERO band data <br> until totally receive Zero Band Value. |
| R02 Cr Lf <br> $<$ READ ACCESSORIES $>$ | BDE-2007 receives signal "RS Cr Lf". |

※ Error message

| BDE 2007 Error <br> number | BDE 2007 Error message |
| :---: | :---: |
| E01 | The format of command is not correct. |
| E02 | The data of command is not correct. |
| E03 | Data not Accept. |
| E04 | Can not execute. |
| E05 | Indicator is busy. |

※If an invalid character is received ? Cr Lf will be sent by the BDE-2007
※If the commands are not accepted for any reason: I Cr Lf will be sent by the BDE-2007
※Batch 1234 S Cr Lf

| 6 | 5 | 4 | 3 | 2 | 1 | 4 | 5 | 6 | 7 | 8 | 9 | 0 | 2 | 3 |  | 4 | 5 | 6 | 6 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 4 Fin | 1 |  |  |  |  |  | 4 SP |  |  |  |  |  |  |  |  |  |  |  |  |


| 1 | 2 | 3 | 4 | 1 | 2 | 3 | 3 | 4 | 1 | 2 |  | 3 | 4 | Cr | Lf |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 4Fr |  |  | 4 Hi |  |  | 4 Lo |  |  |  |  |  |  |  |  |  |  |

※SA Cr Lf format

| 0 | 0 | 3 | 4 | 5 | 6 | Cr | Lf |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

Zero Range
※Please setup F204 first and give command @XX ( $X X=F 204$ )
Ex: @XX R Cr Lf @XX T Cr Lf


* OP-05 Set at Analog 4 ~ 20mA

| Range | $4 \sim 20 \mathrm{~mA}$ (Possible: $2 \sim 22 \mathrm{~mA}$ ) |
| :--- | :--- |
| Resolution | Min. $1 / 3000$ |
| Temp. <br> coefficient | $\pm\left(0.015 \% /{ }^{\circ} \mathrm{Cof} \mathrm{rdg}+\right.$ |
| Max. <br> resistance <br> load | $\operatorname{Max.500\Omega }$ |

Pin1 Pin2 Pin3 Pin4 Pin5

## -If you add a $250 \Omega$ resistor, the output will be 1 V to $5 \mathrm{~V}(4 \sim 20 \mathrm{~mA})$

(i) This resistor must be large enough for proper power consumption.

Use the following formula: $\mathrm{W}=\mathrm{I}^{2} \times \mathrm{R}$
where
W: Power I: Output Current
R: Resistor
If a $500 \Omega$ resistor is used, power consumption will be :
$\mathrm{W}=(0.02)^{2} \times 500=0.2$ when the Output Current is set to 0.2 mA
The resistor should have a power greater than " $0.5 \mathrm{~s}(\mathrm{w}=0.5)$ and have a very low temperature coefficient. In this example power consumption is " 0.2 " and thus, the $500 \Omega$ resistor is adequate.

## -Setting Output Current

IOUT $=\mathrm{IZ}+($ weight $/$ capacity $) *(\mathrm{IM}-\mathrm{IZ}) \quad$ (if $2<=$ IOUT $<=22 \mathrm{~mA})$
IOUT: Output Current IZ: Output at ZERO (F501) IM: Output at Maximum Capacity (F502)
Example: A weighing system has a Maximum Capacity of $10,000 \mathrm{~kg}$.
If you need the Output current to be 4 mA at ZERO display, and 20 mA at $1 / 2$
Maximum Capacity then:
IM $=$ capacity $/$ simulated $) \times($ IOUT -IZ$)+\mathrm{IZ}$
$\mathrm{IM}=10000 / 5000 \times(20 \mathrm{~mA}-4 \mathrm{~mA})+4 \mathrm{~mA}=36 \mathrm{~mA}$
When Output at Full Scale is set at 36 mA , and Output Current at Display ZERO is set at 4 mA , then at $1 / 2$ Capacity $(5000 \mathrm{~kg}$ ) the Output Current will be 20 mA .
※ NOTE: The Maximum Output will be saturated at 24 mA .



If you set at $0-10 \mathrm{~V}$, Please also connect $\mathrm{V}+\mathrm{V}$ - as follows. 。
-If you add a $10 \mathrm{~K} \Omega$ resistor, the output will be 0 mA to $1 \mathrm{~mA}(0 \sim 10 \mathrm{~V})$
(i) This resistor must be large enough for proper power consumption.

Use the following formula: $\quad W=V^{2} / \mathrm{R}$
where
W: Power V: Output Voltage R: Resistor

- Setting Output Voltage

VOUT $=\mathrm{VZ}+($ weight $/$ capacity $) *(\mathrm{VM}-\mathrm{VZ}) \quad($ if $0<=$ VOUT $<=10 \mathrm{~V})$
VOUT: Output Voltage
VZ: Output at ZERO (F503)
VM: Output at Maximum Capacity (F504)
NOTE: The Maximum Output will be saturated at 10 (V).

| Range | $0 \sim+10 \mathrm{~V},($ Possible: -1.25 <br> $11.25 \mathrm{~V})$ |
| :--- | :---: |
| Resolution | Min. $1 / 3000$ |
| Temp. | $\pm\left(0.015 \% /{ }^{\circ} \mathrm{C}\right.$ of $\mathrm{rdg}+$ |
| coefficient | $0.01 \mathrm{~mA}) /{ }^{\circ} \mathrm{C}$ |$|$| Min. $5 \mathrm{~K} \Omega$ |
| :--- |
| Max. |
| resistance |
| load |

§ 6-4 RELAY CONTROL INTERFACE OP-08
**This option is to connecting BDE 2007 OP-01 Control I/0, which enable OP-01 to RELAY OUTPUT.

## Specifications:

## Power : Standard : DC12 from Outside.

Pin assignment :


## Accessory :

(1) 25PIN Male to Female Wire 1.8 Meter.

## (A) RELAY TYPE

Input (IN)
Number of Pins : 8.
Input Common Pin: COM1
Output (OUT):
Number of Pins : 8.
Type : for RELAY.
Max. Load: 250VAC, 30VDC, 3A
Output Common Pin : COM2
RELAY durance : About 100,000 Times.
LED light will ON when work.

## (B) SSR TYPE

Input (IN)
Number of Pins : 8.
Input Common Pin: COM1
Output (OUT):
Number of Pins: 8.
Type : for RELAY.
Max. Load: 24~280VAC, 3A (Only for AC)

| CONTROL I/O Pins |  |  |
| :---: | :---: | :---: |
| $\begin{gathered} \text { OP-08 } \\ \text { I/O } \end{gathered}$ |  | BDE-2007 |
|  |  | Control I/O |
| Input | 1 | PIN 25 |
|  | 2 | PIN 24 |
|  | 3 | PIN 23 |
|  | 4 | PIN 22 |
|  | 5 | PIN 21 |
|  | 6 | PIN 20 |
|  | 7 | PIN 19 |
|  | 8 | PIN 18 |
| Output | 1 | PIN 13 |
|  | 2 | PIN 12 |
|  | 3 | PIN 11 |
|  | 4 | PIN 10 |
|  | 5 | PIN 9 |
|  | 6 | PIN 8 |
|  | 7 | PIN 7 |
|  | 8 | PIN 6 |

Output Common Pin : COM2
RELAY durance : About 100,000 Times.
LED light will ON when work.

| Data Register |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| R/W | Type | Function | Address | Modbus <br> address | Description |
| R | Word | R:04 | $0000 \sim 0001$ |  | Same as <br> display |
| R | Word | R:04 | $0002 \sim 0003$ | $30003 \sim 30004$ | G.W. |
| R | Word | R:04 | $0004 \sim 0005$ | $30005 \sim 30006$ | N.W. |
| R | Word | R:04 | $0006 \sim 0007$ | $30007 \sim 30008$ | Tare Value |
| R | Word | R:04 | $0008 \sim 0009$ | $30009 \sim 30010$ | Accumulation |
| R | Word | R:04 | $0010 \sim 0011$ | $30011 \sim 30012$ | Total Count |
| R | Word | R:04 | $0012 \sim 0013$ | $30013 \sim 30014$ | Actual Final |
|  |  |  |  |  |  |
| R/W | Word | R:03,W:06 | $0000 \sim 0001$ | $40001 \sim 40002$ | Final |
| R/W | Word | R:03,W:06 | $0002 \sim 0003$ | $40003 \sim 40004$ | SP1 |
| R/W | Word | R:03,W:06 | $0004 \sim 0005$ | $40005 \sim 40006$ | SP2 |
| R/W | Word | R:03,W:06 | $0006 \sim 0007$ | $40007 \sim 40008$ | FF |
| R/W | Word | R:03,W:06 | $0008 \sim 0009$ | $40009 \sim 40010$ | HI |
| R/W | Word | R:03,W:06 | $0010 \sim 0011$ | $40011 \sim 40012$ | LO |


| Bit I/O |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| R/W | Type | Function | Address | Modbus <br> address | SCALE <br> Output |
| R | Bit | R:02 | $\mathbf{0 0 0 0}$ | $\mathbf{1 0 0 0 1}$ | ZERO |
| R | Bit | R:02 | $\mathbf{0 0 0 1}$ | $\mathbf{1 0 0 0 2}$ | M.D. |
| $R$ | Bit | R:02 | $\mathbf{0 0 0 2}$ | $\mathbf{1 0 0 0 3}$ | G.W. |
| R | Bit | R:02 | $\mathbf{0 0 0 3}$ | $\mathbf{1 0 0 0 4}$ | N.W. |
| $R$ | Bit | R:02 | $\mathbf{0 0 0 4}$ | $\mathbf{1 0 0 0 5}$ | Tared |
| $R$ | Bit | R:02 | $\mathbf{0 0 0 5}$ | $\mathbf{1 0 0 0 6}$ | OVER |
|  |  |  |  |  |  |
| $R$ | Bit | R:02 | $\mathbf{0 0 3 0}$ | $\mathbf{1 0 0 4 9}$ | Range |
| $R$ | Bit | R:02 | $\mathbf{0 0 3 1}$ | $\mathbf{1 0 0 5 0}$ | SP1 |
| $R$ | Bit | R:02 | $\mathbf{0 0 3 2}$ | $\mathbf{1 0 0 5 1}$ | SP2 |
| $R$ | Bit | R:02 | $\mathbf{0 0 3 3}$ | $\mathbf{1 0 0 5 2}$ | FF |
| $R$ | Bit | R:02 | $\mathbf{0 0 3 4}$ | $\mathbf{1 0 0 5 3}$ | HI |
| $R$ | Bit | R:02 | $\mathbf{0 0 3 5}$ | $\mathbf{1 0 0 5 4}$ | LO |
| $R$ | Bit | R:02 | $\mathbf{0 0 3 6}$ | $\mathbf{1 0 0 5 5}$ | Finish |
| $R$ | Bit | R:02 | $\mathbf{0 0 3 7}$ | $\mathbf{1 0 0 5 6}$ | Unstable |
| / Error |  |  |  |  |  |


| Bit I/O |  |  |  |  |  |
| :--- | :---: | :---: | :---: | :---: | :---: |
| R/W | Type | Function | Address | Modbus <br> Address | SCALE <br> Intput |
| R/W | Bit | R:01,W:05 | $\mathbf{0 0 0 0}$ | $\mathbf{0 0 0 0 1}$ | ZERO |
| R/W | Bit | R:01,W:05 | $\mathbf{0 0 0 1}$ | $\mathbf{0 0 0 0 2}$ | TARE |
| R/W | Bit | R:01,W:05 | $\mathbf{0 0 0 2}$ | $\mathbf{0 0 0 0 3}$ | TARE Cleared |
| R/W | Bit | R:01,W:05 | $\mathbf{0 0 0 3}$ | $\mathbf{0 0 0 0 4}$ | Display G.W. |
| R/W | Bit | R:01,W:05 | $\mathbf{0 0 0 4}$ | $\mathbf{0 0 0 0 5}$ | Display N.W. |
|  |  |  |  |  |  |
| R/W | Bit | R:01,W:05 | $\mathbf{0 0 3 0}$ | $\mathbf{0 0 0 4 9}$ | Add 1 |
| R/W | Bit | R:01,W:05 | $\mathbf{0 0 3 1}$ | $\mathbf{0 0 0 5 0}$ | Clear ACC and <br> Count |
| R/W | Bit | R:01,W:05 | $\mathbf{0 0 3 2}$ | $\mathbf{0 0 0 5 1}$ | Start Batch |
| R/W | Bit | R:01,W:05 | $\mathbf{0 0 3 3}$ | $\mathbf{0 0 0 5 2}$ | Stop Batch |





## ※BDE-2007 MODBUS SAMPLE CODE ※Error Code :

EX: Read as display: 01040000000271 CB
EX : Read as N.W. : 010400020002 D0 0B
EX : Read Final weight: 010300000002 C 4 0B
EX: Read SP1weight: 01 030002000265 CB
EX : Write 5000 to Final weight :
01060000138884 9C
EX : Write 300 to SP1 Value :
01060002 0B B8 2F 48
EX: Read ZERO status : 010200000001 B9 CA
EX : Read ZERO Range : 010200300001 B9 C5
EX : Write ZERO to BDE 2007 :
01050000 FF 00 8C 3A

Appendix 2

【Screen characters】


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## 플․․․․ Benediction Enterprise Co., Ltd, Taiwan



## 20090602 VER.

# BOE 2007 Weighing nndicator S controller User's Manual 

